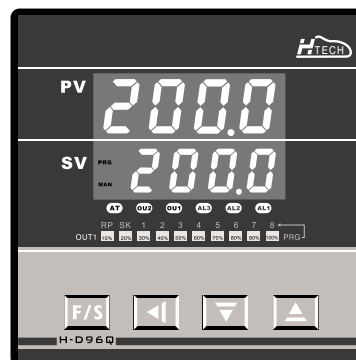
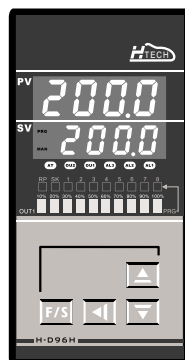
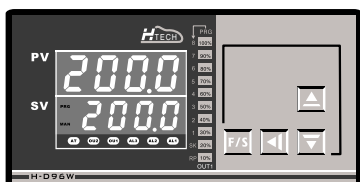


# Microprocessor PID controller



H-D72 H-D96Q  
H-D48 H-D96W H-D96H



## Display unit & Indication lamps

|                   |  |
|-------------------|--|
| <b>PV</b>         | = Measured value display                     |
| <b>SV</b>         | = Set value display                          |
| <b>AL1</b>        | = Alarm 1 output lamp                        |
| <b>AL2</b>        | = Alarm 2 output lamp                        |
| <b>AL3</b>        | = Alarm 3 output lamp                        |
| <b>OU1</b>        | = Control output 1 lamp                      |
| <b>OU2</b>        | = Control output 2 lamp                      |
| <b>AT</b>         | = Autotuning lamp                            |
| <b>MAN</b>        | = Manual mode lamp                           |
| <b>10% ~ 100%</b> | = Manipulated output value display           |
| <b>PRG</b>        | = Programmable mode lamp                     |
| <b>1~8</b>        | = Segment-in-process display lamp            |
| <b>RP</b>         | = Ramping mode lamp (programmable mode only) |
| <b>SK</b>         | = Soaking mode lamp (programmable mode only) |

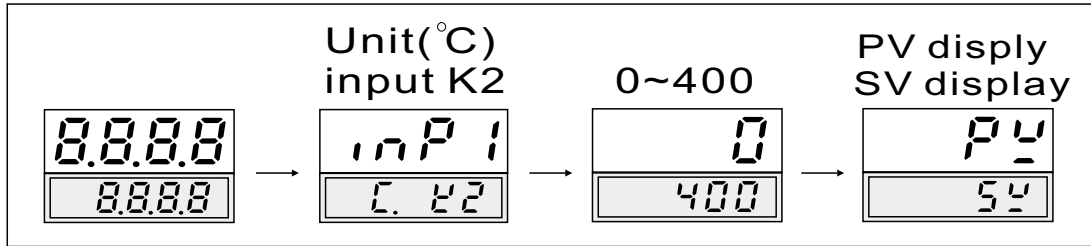
## Operation keys

|                 |  |
|-----------------|--|
| <b>F/S</b>      | = Function & Set key   |
| <b>◀</b>        | = Shift key  |
| <b>▼</b>        | = Down key   |
| <b>▲</b>        | = Up key   |
| <b>▲</b> 3sec   | Press 3 sec while the SV is not flashing = Used for returning to initial window  |
| <b>▼</b> 3sec   | Press 3 sec while in level selection window = Used for calling up lock function  |
| <b>▼</b> 3sec   | Press 3 sec while in pv/sv initial window = Used for stopping output and SV window will display "HOLD", <b>▲</b> press 3 sec again to regain output<br>(This function is available only while OUTM is selected 1 or 2) |
| <b>F/S</b> 3sec | Press 3 sec while in pv/sv initial window = Used for calling up level selection  |
| <b>F/S</b> 3sec | Press 3 sec while in level selection window = Used for entering each level   |

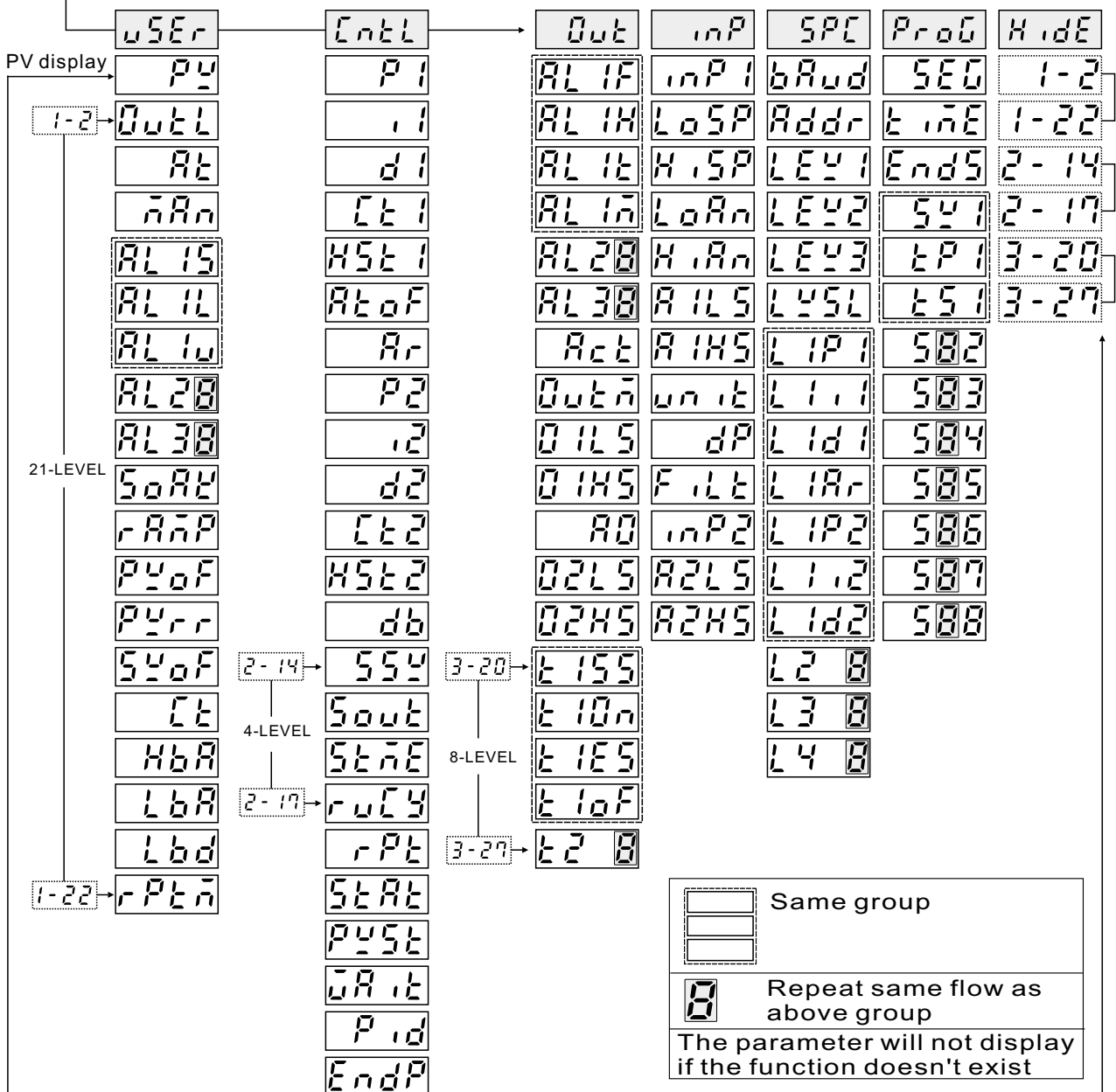
## Operation keys (programmable mode only)

|   |       |   |
|---|-------|---|
| These keys are only operated in PV/SV initial window            |       |   |
| <b>▲</b> 3sec   | Run   | PRG lights, RP or SK flashes The executing segment lamp lights            |
| <b>▼</b> 3sec   | Pause | PRG, RP and SK light The executing segment lamp lights                    |
| <b>▲</b> + <b>F/S</b>   | Jump  | Jump to the next segment, press <b>▲</b> first                            |
| <b>▼</b> + <b>F/S</b>   | Stop  | Turn off all lamps which used for programmable mode, press <b>▼</b> first |
| Refer to arrow <b>◀</b> When PRG Lights (No PRG light in H-D48) |       |   |

# Window checks display after turning on power

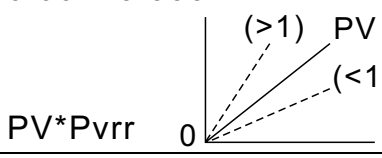


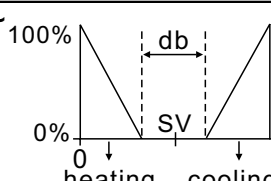
## LEVEL Parameter flow chart



| Parameter    | DESCRIPTION   | RANGE     | Initial value |
|--------------|---------------|-----------|---------------|
| <i>PV</i> Pv | Process value | LoSP~HiSP |               |
| <i>SV</i> Sv | Set value     | LoSP~HiSP | 0.0           |

*USER* ▼

|                  |  |   |       |
|------------------|--|---|-------|
| <i>OutL</i> OutL | Output percentage  | 0.0~100.0%  | 0.0   |
| <i>At</i> At     | Auto tuning  | No / yes  | no    |
| <i>Man</i> Man   | Manual mode  | Man1 =power failure memory<br>Man2 =no memory No =non   | no    |
| <i>AL1S</i> AL1S | Alarm 1 set value  | If ALIF set at 1 or 2 range=-200~200<br>If ALIF set at 3 or 4 range=Losp~Hisp<br>If ALIF set at 10 range =1-8<br>segment ending | 10.0  |
| <i>AL1L</i> AL1L | Alarm 1 lower set value  | 0~200   | 10.0  |
| <i>AL1u</i> AL1u | Alarm 1 upper set value  | 0~200   | 10.0  |
| <i>AL2S AL3S</i> | AL2S / AL3S For operating functions refer to the above descriptions                    |   |       |
| <i>SoAK</i> SoAK | Perform only when AL1M set at 10 or 11 refer to explanation on page 7                  | 0.00~99.59 (h.m)  | 0.00  |
| <i>rAmP</i> rAmP | Ramp<br>refer to explanation on page 7   | 0.0~200.0/m   | 0.0   |
| <i>Pvof</i> Pvof | Pv offset<br>refer to explanation on page 7  | -200~200  | 0.0   |
| <i>Pvrr</i> Pvrr | Pv ratio<br>refer to explanation on page 7   | 0.001~9.999<br>                             | 1.000 |
| <i>SvoF</i> SvoF | Sv offset<br>refer to explanation on page 7  | -200~200  | 0.0   |
| <i>Ct</i> Ct     | Current transformer monitor<br>refer to explanation on page 7                          | 0.0~100.0A  |       |
| <i>HbA</i> HbA   | Heater break alarm value<br>refer to explanation on page 8                             | 0.1~100.0A  | 0.1   |
| <i>LbA</i> LbA   | Control loop break alarm time<br>refer to explanation on page 8                        | 0.1~200.0 min   | 8.0   |
| <i>Lbd</i> Lbd   | LBA dead band<br>refer to explanation on page 8  | 0.0~200.0   | 0.0   |
| <i>rPtm</i> rPtm | Repeat times monitor<br>Only use in program function<br>refer to explanation on page 8 | 1~1000  |       |

| Parameter        | DESCRIPTION  | RANGE   | Initial value |
|------------------|--|---|---------------|
| <b>Ctrl</b> ▼    |  |   |               |
| <i>P1</i> P1     | Output 1 proportional band   | 0.0~3000  | 30.0          |
| <i>i1</i> i1     | Output 1 integral time   | 0~3600 sec  | 240           |
| <i>d1</i> d1     | Output 1 derivative time   | 0~900 sec   | 60            |
| <i>Ct1</i> Ct1   | Output 1 cyclic time<br>refer to explanation on page 8                                 | 0~150 sec   | 15            |
| <i>HSt1</i> HSt1 | Output 1 hysteresis  | 0.0~200.0   | 0.0           |
| <i>AtoF</i> AtoF | At offset<br>refer to explanation on page 8  | -200~200  | 0.0           |
| <i>Ar</i> Ar     | Anti-reset windup<br>refer to explanation on page 8                                    | 0~100.0% SV-P1 x Ar   | 100.0         |
| <i>P2</i> P2     | Output 2 proportional band   | 0.0~3000  | 30.0          |
| <i>i2</i> i2     | Output 2 integral time   | 0~3600 sec  | 240           |
| <i>d2</i> d2     | Output 2 derivative time   | 0~900 sec   | 60            |
| <i>Ct2</i> Ct2   | Output 2 cyclic time   | 0~150 sec   | 15            |
| <i>HSt2</i> HSt2 | Output 2 hysteresis  | 0.0~200.0   | 0.0           |
| <i>db</i> db     | Dead band/overlap  | -200.0~200.0<br> | 0.0           |
| <i>SSv</i> SSv   | Soft start set value<br>refer to explanation on page 8                                 | 0.0~200.0 (see fig 2)   | 120.0         |
| <i>Sout</i> Sout | Soft start output percentage<br>refer to explanation on page 8                         | 0.0~100.0% (see fig 2)  | 30.0          |
| <i>StmE</i> StmE | Soft start failed time<br>refer to explanation on page 8                               | 0~10 min (see fig 2)  | 10            |
| <i>ruCy</i> ruCy | Motor valve cyclic time<br>refer to explanation on page 8                              | 1~150 sec (see fig 3)   | 5             |
| <i>rPt</i> rPt   | Program executing times<br>refer to explanation on page 8                              | 1~1000 (see fig 4)  | 1             |
| <i>StAt</i> StAt | Start mode selection<br>use in program function only<br>refer to explanation on page 8 | CoLd = manual<br>rSET=start after power ON<br>Hot=<br>start from memory of power failure              | CoLd          |
| <i>PvSt</i> PvSt | Start point selection<br>use in program function only                                  | RSEt = start from 0<br>Pv = start from PV   | rSEt          |
| <i>wAit</i> wAit | Wait value in program<br>refer to explanation on page 8                                | 0.0~200.0   | 0.0           |
| <i>Pid</i> Pid   | PID/Level PID selection<br>refer to explanation on page 9                              | Pid =Pid<br>Lpid =Level Pid   | Pid           |
| <i>EndP</i> EndP | Selects control when program ended<br>refer to explanation on page 9                   | Cont = Continue<br>StoP = One program only<br>(see fig 4)   | StoP          |

| Parameter  | DESCRIPTION  | RANGE   | Initial value |
|--|--|---|---------------|
| <b>Out</b> ▼   |  |   |               |
| <i>AL 1F</i> AL1F  | Alarm 1 action function  | 0~12 (see table 1)  | 1             |
| <i>AL 1H</i> AL1H  | Alarm 1 hysteresis   | 0.0~200.0   | 0.0           |
| <i>AL 1t</i> AL1t  | Alarm 1 in program mode on time  | 0.00~99.59 (h · m)  | 0.00          |
| <i>AL 1m</i> AL1m  | Alarm 1 special mode selection   | (see table 2)   | 0             |
| For operating functions refer to the above descriptions<br>Different function see(1),(2),(3) |  |   |               |
| <i>AL 2F</i> AL2F  | (1)AL2M Alarm 2 special mode selection (See Table 2 )  | 0~7   |               |
| <i>AL 3F</i> AL3F  | (2)AL3F Alarm 3 action function (See Table 1 )   | 0~11  |               |
| <i>AL 3M</i> AL3M  | (3)AL3M Alarm 3 special mode selection (see Table 2 )  | 0~7   |               |
| <i>Act</i> Act   | Control action selection   | Cool / HEAT   | HEAT          |
| <i>Outm</i> Outm   | Output mode selection<br>This parameter is skipped,<br>opening it needs to contact distributor (see table 3) |   | 1             |
| <i>O1LS</i> O1LS   | Output 1 scale low   | 0.0~100.0%  | 17.6          |
| <i>O1HS</i> O1HS   | Output 1 scale high  | 0.0~100.0%  | 96.0          |
| <i>AO</i> AO   | Analog output selection  | Pv=transmit PV<br>Sv=transmit SV<br>dEv=transmit (PV-SV)<br>Mv=transmit output percentage | Pv            |
| <i>O2LS</i> O2LS   | Output 2 scale low   | 0.0~100.0%  | 17.6          |
| <i>O2HS</i> O2HS   | Output 2 scale high  | 0.0~100.0%  | 96.0          |
| <i>t1SS</i> t1SS   | Time signal 1 start segment setting<br>Use in program function only<br>refer to explanation on page 9        | 1~8   | 1             |
| <i>t1On</i> t1On   | Time signal 1 on time setting<br>Use in program function only<br>refer to explanation on page 9              | 0.00~99.59 (h · m)  | 0.01          |
| <i>t1ES</i> t1ES   | Time signal 1 end segment setting<br>Use in program function only<br>refer to explanation on page 9          | 1~8   | 1             |
| <i>t1oF</i> T1oF   | Time signal 1 off time setting<br>Use in program function only<br>refer to explanation on page 9             | 0.00~99.59 (h · m)  | 0.01          |
| <i>t2SS</i> t2SS   | For operating functions refer to the above descriptions  |   |               |

| Parameter      | DESCRIPTION         | RANGE   | Initial value                         |   |       |
|----------------|---------------------|---|---------------------------------------|---|-------|
| <b>inP</b> ▼   |                     |   |                                       |   |       |
| <b>inP1</b>    | inP1                | Input 1 selection   | (see table 4)                         | K2  |       |
| <b>LoSP</b>    | LoSP                | Low setting limit   | LOSP~HiSP                             | 0.0   |       |
| <b>HiSP</b>    | HiSP                | High setting limit  | LOSP~HiSP                             | 400.0   |       |
| <b>LoAn</b>    | LoAn                | Analog input range low<br>refer to on page 21                                     | -1999~9999                            | 0.0   |       |
| <b>HiAn</b>    | HiAn                | Analog input range high<br>refer to on page 21                                    | -1999~9999                            | 100.0   |       |
| <b>A1LS</b>    | A1LS                | Analog input 1 scale low<br>refer to on page 21                                   | 0~FFFF                                |   |       |
| <b>A1HS</b>    | A1HS                | Analog input 1 scale high<br>refer to on page 21                                  | 0~FFFF                                |   |       |
| <b>unit</b>    | unit                | Unit selection  | °C/°F/non                             | °C  |       |
| <b>dP</b>      | dP                  | Decimal point   | 0/0.0/0.00/0.000                      | 0.0   |       |
| <b>FiLt</b>    | FiLt                | Digital filter (see fig 5)  | 0.001~1.000                           | Non = no function<br>Ct = use for heater break alarm<br>rmSV= use for remote SV | 0.900 |
| <b>inP2</b>    | inP2                | Input 2 selection   |                                       | non   |       |
| <b>A2LS</b>    | A2LS                | Analog input 2 scale low  | 0~FFFF                                |   |       |
| <b>A2HS</b>    | A2HS                | Analog input 2 scale high   | 0~FFFF                                |   |       |
| <b>SPC</b> ▼   |                     |   |                                       |   |       |
| <b>bAud</b>    | bAud                | Baud rate   | 2.4K / 4.8K / 9.6K<br>19.2K / 38.4K   | 9.6K  |       |
| <b>Addr</b>    | Addr                | Address   | 0~31                                  | 0   |       |
| <b>Lev1</b>    | Lev1                | Set the range for level1 PID (see fig 6)<br>(act only when level PID is selected) | LoSP~HiSP                             | 400   |       |
| <b>Lev2</b>    | Lev2                | Set the range for level2 PID (see fig 6)<br>(act only when level PID is selected) | LoSP~HiSP                             | 400   |       |
| <b>Lev3</b>    | Lev3                | Set the range for level3 PID (see fig 6)<br>(act only when level PID is selected) | LoSP~HiSP                             | 400   |       |
| <b>LvSL</b>    | LvSL                | Watched PID level selection, the level is selected which will display below       | 1~4<br>refer to explanation on page 9 | 1   |       |
| <b>L1P1</b>    | L1P1                | Output 1 proportional band for level 1  | 0.0~3000                              | 30.0  |       |
| <b>L1i1</b>    | L1i1                | Output 1 integral time for level1   | 0~3600 sec                            | 240   |       |
| <b>L1d1</b>    | L1d1                | Output 1 derivative time for level1   | 0~900 sec                             | 60  |       |
| <b>L1Ar</b>    | L1Ar                | Anti-reset windup for level1  | 0.0~100.0%                            | 100.0   |       |
| <b>L1P2</b>    | L1P2                | Output 2 proportional band for level 1  | 0.0~3000 sec                          | 30.0  |       |
| <b>L1i2</b>    | L1i2                | Output 2 integral time for level1   | 0~3600 sec                            | 240   |       |
| <b>L1d2</b>    | L1d2                | Output 2 derivative time for level 1  | 0~900                                 | 60  |       |
| <b>L2P ~ 4</b> | The same as level 1 |   |                                       |   |       |

| Parameter     | DESCRIPTION                                   | RANGE            | Initial value |
|---------------|---|------------------|---------------|
| <b>Prog</b> ▼ |   |                  |               |
| 5EG SEG       | Program segment monitor                       | 1~8              |               |
| t nE Time     | Program countdown monitor                     |                  |               |
| EndS EndS     | Program segment end setting                   | 1~8              | 1             |
| 541 Sv1       | Sv in segment 1 (see fig 7)                   | LoSP~HiSP        | 100           |
| tP1 tP1       | Program time in segment 1 (see fig 7)         | 0.00~99.59 (H.M) | 0.00          |
| tS1 tS1       | Soak time in segment 1 (see fig 7)            | 0.00~99.59 (H.M) | 0.00          |
| 542~8         | The same as segment 1                         |                  |               |
| <b>Hide</b> ▼ |   |                  |               |
| 1-2~1-22      | Parameter shows with respect to this position | non~t2of         |               |
| 2-14~2-17     | Parameter shows with respect to this position | non~t2of         |               |
| 3-20~3-27     | Parameter shows with respect to this position | non~t2of         |               |

## PARAMETER EXPLANATIONS

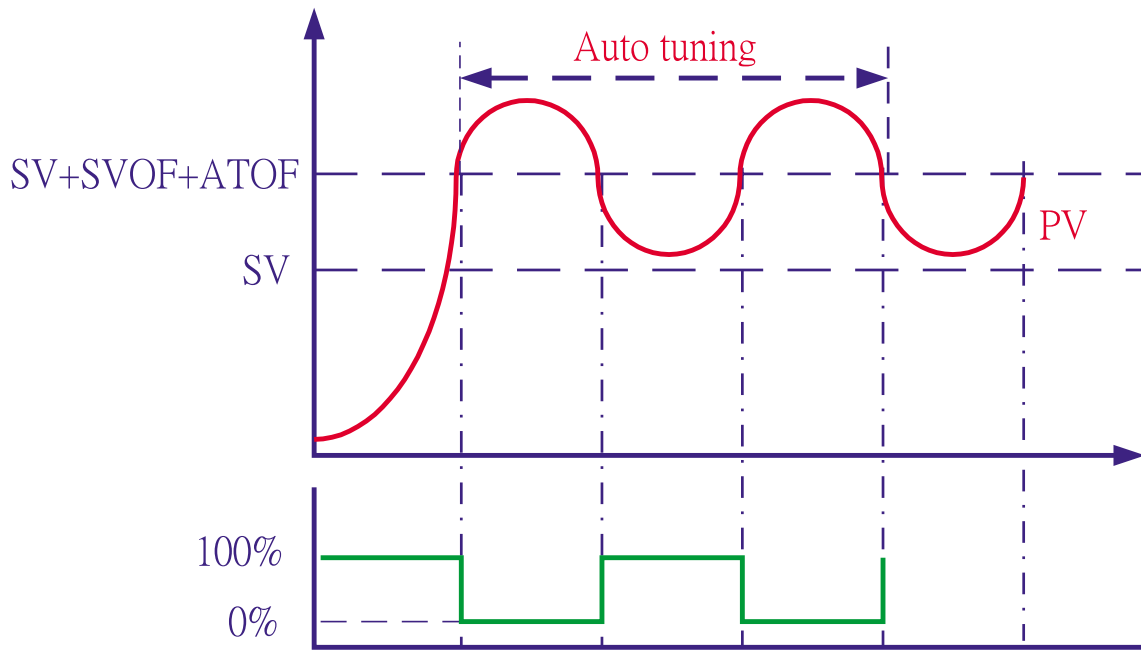
|      |   |
|------|---|
| SoAK | It performs only when AL1M set at 10 or 11, and the controller is without program function. If you set AL1M at 10, then AL1 shifts to soak function and contactor is normal open; if you set AL1M at 11, then AL1 shifts to soak function but contactor is normal close.        |
| rAmP | It's for setting that PV will be increased or decreased by set value if the controller is without program function.<br>For example:<br>If rAmP is set at 10, then the PV will increase 10°C per minute, but if PV is higher than SV, then the PV will decrease 10°C per minute. |
| PvoF | It's for setting that if PV is not correct to SV, then you can adjust it with (+) or (-).   |
| Pvrr | It's for adjusting PV be more accurate. The formulation is PV (now) = PV (pre) X Pvrr + PVOF.   |
| SvoF | It's for setting that if SV is not correct to PV, then you can adjust it with (+) or (-).   |
| Ct   | It's for detecting current to find if the heater is broken. Display value:0.0~100.0A. When you order CT function,a small C.T. is included.  |

|           |   |
|-----------|---|
| HbA       | <p>Heater break alarm set value. Set value range: 0.1 ~100.0 A.<br/>For Example:<br/>a. When Low or no current flow, but control output is On, and <math>CT \leq HBA</math>, it means heater is broken, then the alarm is on.<br/>a.b. When over current or short-circuit, but control output is off, and <math>CT \geq HBA</math>, then the alarm is on.<br/>(The CT and HBA parameter works only when you order Heater break alarm function).</p> |
| LbA & Lbd | <p>They are parameters for Loop Break Alarm.<br/>For Example:<br/>When Out1:0.0%, LBA time elapsed, PV should be below LBD, if it is still within LBD determination range, alarm is on .<br/>When Out1:100.0%, LBA time elapsed, PV should be upper LBD, if it is still within LBD determination range, alarm is on .<br/>(LBA and LBD works by software setting, no need to order extra components).</p>   |
| rPtm      | <p>It shows how many times of running program at the moment.<br/>This parameter works when your PID controller opens on program function.</p>   |
| Ct1       | <p>It's for setting ON-OFF cyclic time of output 1, normally it is set at 0 for 4~20Ma output, 1 for SSR drive output, 15 for relay output.</p>   |
| Ar        | <p>It's a solution for preventing over-shooting.<br/>This parameter makes Integral delay. The setting range is from 0 to 100%, initial value 100% means integral will perform when PV reaches proportional band, but if you set Ar at 50%, it means integral will perform when PV reaches 50% of proportional band.</p>   |
| SSV       | <p>It's for setting soft start range, when you want the heating system doesn't go up too quick at the beginning, you may set SSV.<br/>For Example:<br/>You want the temperature going up slowly under 120°C, you may set SSV at 120.</p>  |
| Sout      | <p>It is for setting the output percentage under SSV , if you want 50% of output, you may set it at 50 .</p>  |
| StmE      | <p>It is for setting soft start failure time. When the PID controller reaches the StmE time, but PV doesn't reach SSV, it means soft start failure, then Controller will revert to SV.</p>  |
| RuCy      | <p>Motor valve cyclic time, it means the time from close to open or from open to close.</p>   |
| rPt       | <p>It's for setting how many times of program process to be executed.</p>   |
| StAt      | <p>It is for setting when it starts program procedure, cold is by manual, Rset is to start after power on. Hot is to start from memory of power failure.</p>  |
| wAit      | <p>It is for setting the value that SV will wait PV if PV goes up slowly than SV.</p>   |



|             |  |
|-------------|--|
| <b>Pid</b>  | In this parameter, you can choose the controller with one PID performing only or level-PID (LPID) performing, if you choose LPID then you can set 4 levels of different PID.   |
| <b>Endp</b> | It is for setting when program is ending, one program only or to be continued.   |
| <b>tiSS</b> | t1SS is for time signal alarm to set which segment you want it to start alarm (in program function).<br>For Example:<br>You want it alarms at segment 2, then you may set it to 2 .  |
| <b>tiOn</b> | t1On is to set what time do you want alarm to perform.<br>For Example:<br>You want it alarms at 6 min. (if your segment 2 set at 10 min.), you may set it to 6 , then the alarm will perform in segment 2, but start from 6 <sup>th</sup> min.                                   |
| <b>t1Es</b> | t1ES is to set which segment you want to end alarm (in program function).<br>For Example:<br>You want it ends at segment 5, then you may set it to 5 .   |
| <b>T1oF</b> | T1oF is to set what time do you want alarm to end.<br>For Example:<br>You want it ends at 3 min. (if your segment 5 set at 5 min.), you may set it to 3 , then the alarm will end at 3 <sup>rd</sup> min. of segment 5.  |
| <b>LvsL</b> | LvSL is for level PID use, which level of PID you have set, then you can watch its PID value.<br>For Example:<br>You set it to 3 , then you can watch L3P1, L3I1, L3d1 .....<br>But in first you need to set Lpid at Pid parameter in level Cntl and Lev1 to Lev 3 in SPC level. |

# Fig 1. PID Auto Tuning



# Fig 2. Soft Start

SSV

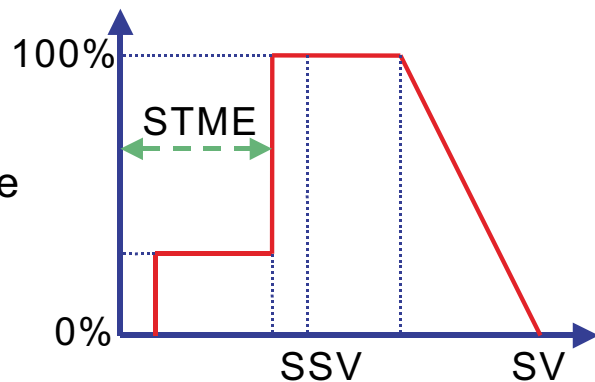
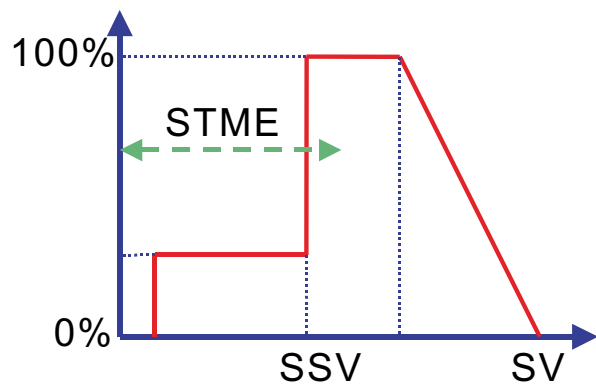
Soft start set value

SOUT

Soft start output percentage

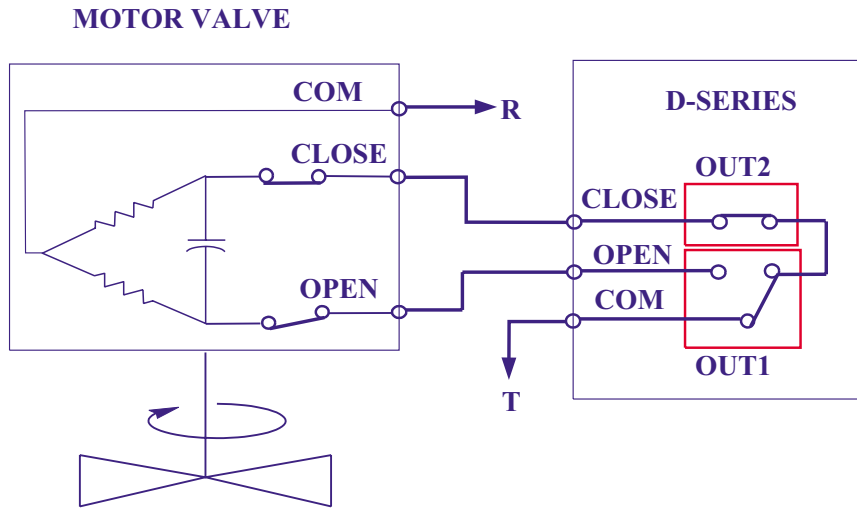
STME

Soft start failed time



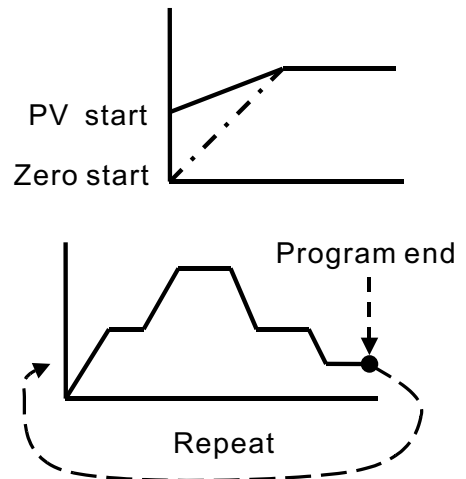
# Fig 3. Motor Valve Control

RUCY  
Motor valve cyclic time

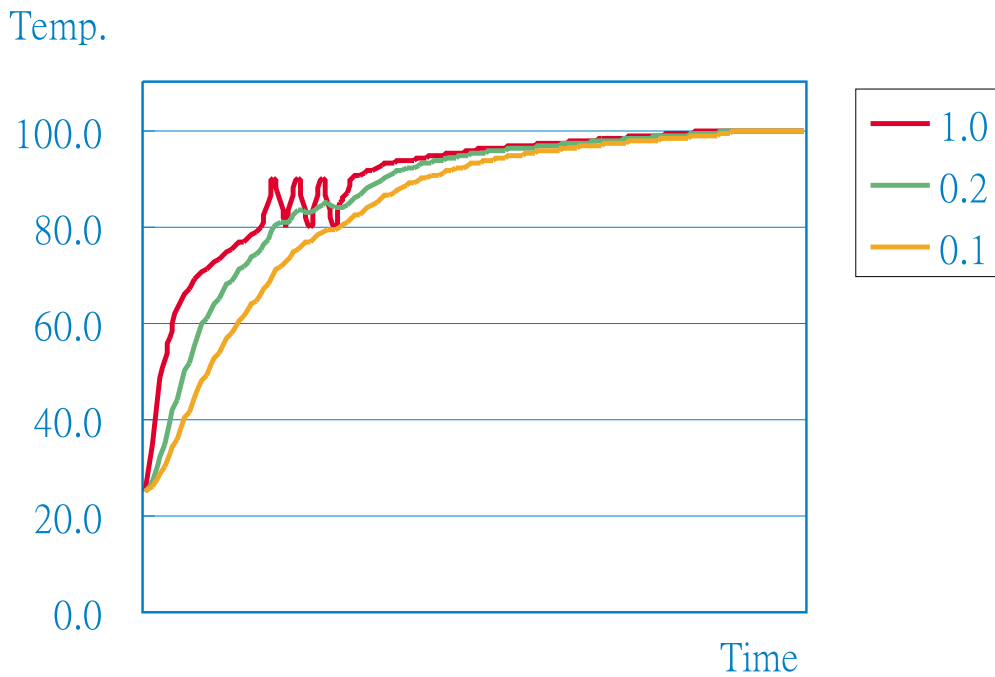


# Fig 4. Program Control

|      |                                    |
|------|------------------------------------|
| RPTM | Repeat times monitor               |
| RPT  | Program execution times setting    |
| STAT | Start mode selection               |
| PVST | Start point selection              |
| WAIT | Wait zone                          |
| ENDP | Selects control when program ended |
| SEG  | Program segment monitor            |
| TIME | Program countdown monitor          |
| ENDS | Program end segment setting        |

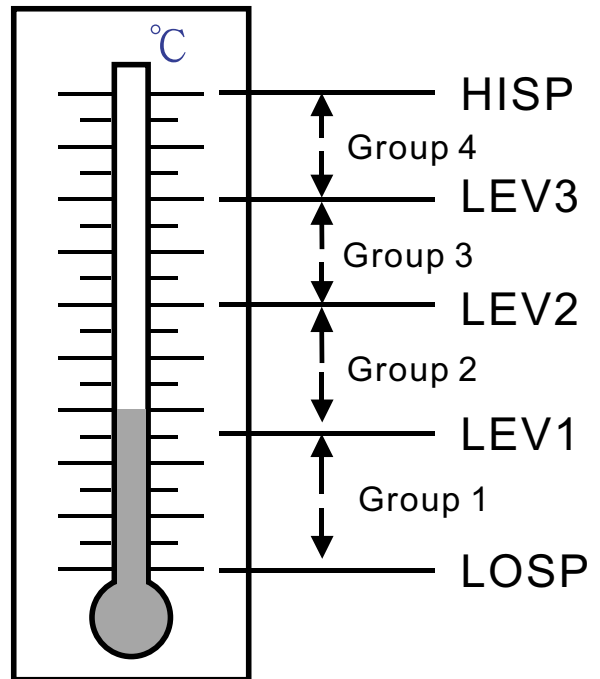


# Fig 5. Digital Filter

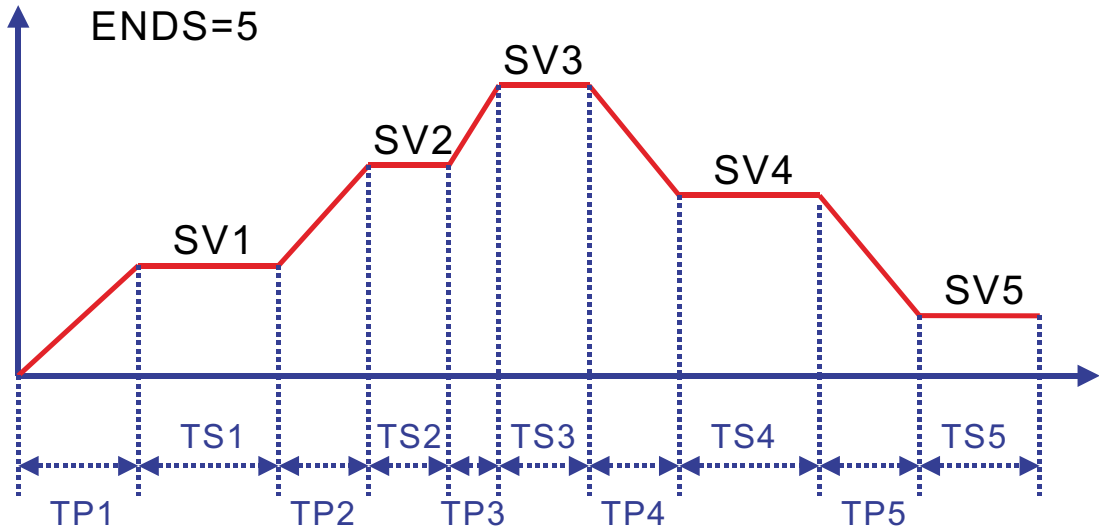


# Fig 6. Level PID

| PID  | PID/level PID selection |
|------|-------------------------|
| LEV1 | Level 1                 |
| LEV2 | Level 2                 |
| LEV3 | Level 3                 |
| LVSL | Levels selection        |
| L1P1 | P1 for group 1          |
| L1I1 | I1 for group 1          |
| L1D1 | D1 for group 1          |
| L1AR | AR for group 1          |
| L1P2 | P2 for group 1          |
| L1I2 | I2 for group 1          |
| L1D2 | D2 for group 1          |



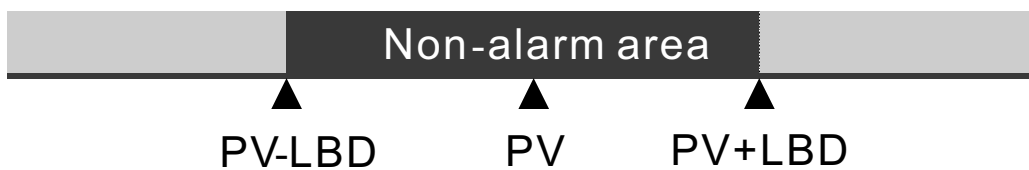
# Fig7. Program Control



# Fig8. Loop Break Alarm

OUTL=0.0%  
LBA time elapsed  
PV is still within  
determination range

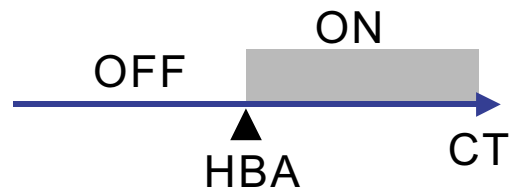
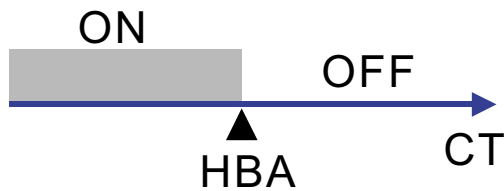
OUTL=100.0%  
LBA time elapsed  
PV is still within  
determination range



# Fig 9. Heater Break Alarm

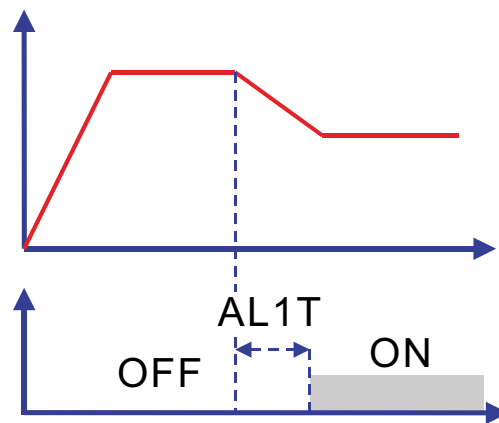
Low or No current flow  
 Control output is ON  
 $CT \leq HBA$

Over current or short-circuit  
 Control output is OFF  
 $CT \geq HBA$

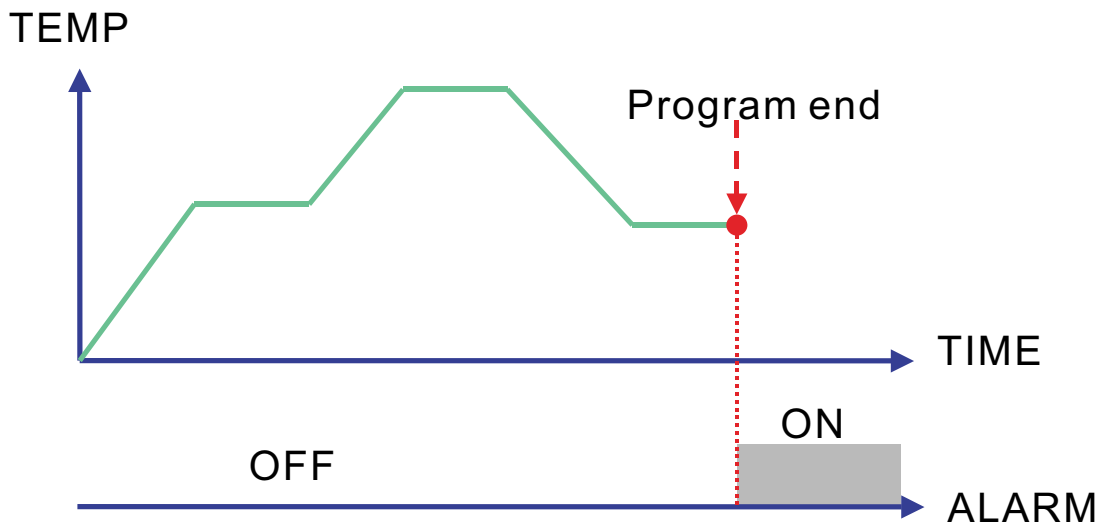


# Fig 10. Segment Ending Alarm

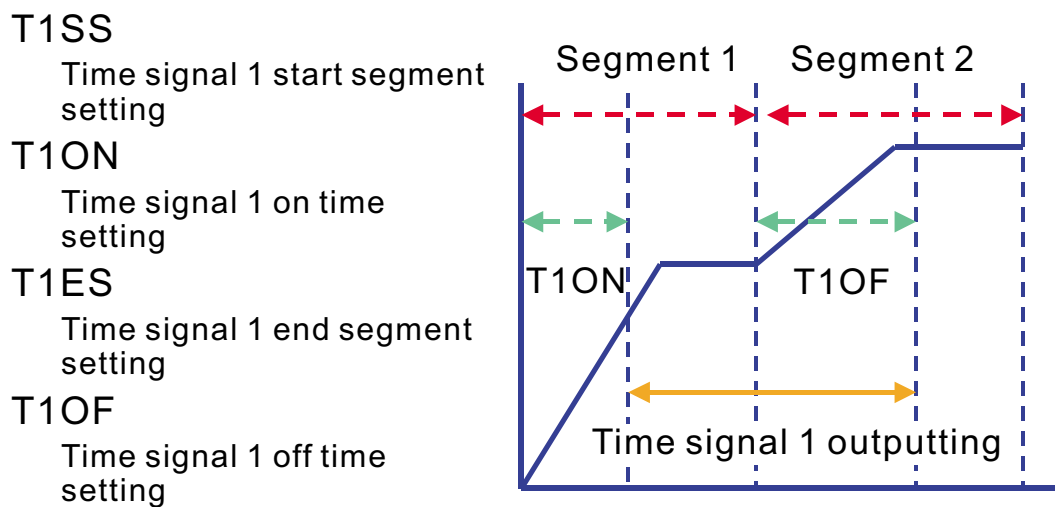
AL1F  
 10  
 AL1S  
 1~8 segment  
 AL1T  
 0.00  
 Flicker alarm  
 99.59  
 Continued alarm  
 Others  
 ON delay time



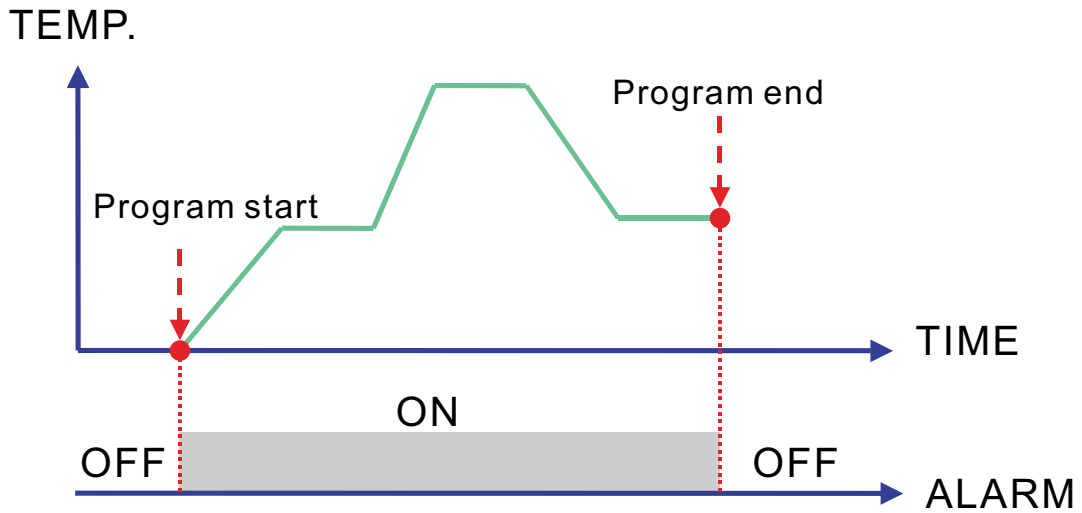
# Fig 11. Program Ending Alarm



# Fig 12. Time Signal Alarm



# Fig 13. Program Running Alarm



# Fig 14. Communication Protocol

## Interface

RS-485  
RS-232

## Baud rate

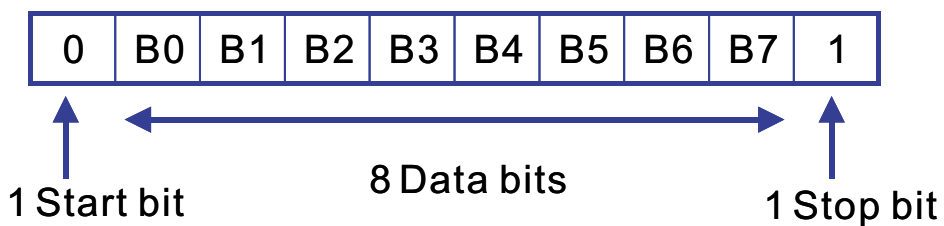
2400  
4800  
9600  
19200  
38400

## Data frame

Data Bits = 8  
Parity = None  
Start bit = 1  
Stop bit = 1

## Data format

ModBus Protocol RTU  
Mode





**Table 1. Alarm Mode Selection**  
(Used in Parameter AL1F,AL2F,AL3F)

| AL1F | AL2F | AL3F | Alarm function selection                             |            |
|------|------|------|--|------------|
| 0    | 0    | 0    | No alarm   |            |
| 1    | 1    | 1    | Deviation high alarm                                 |            |
| 2    | 2    | 2    | Deviation low alarm                                  |            |
| 3    | 3    | 3    | Absolute high alarm                                  |            |
| 4    | 4    | 4    | Absolute low alarm                                   |            |
| 5    | 5    | 5    | Deviation high/low alarm                             |            |
| 6    | 6    | 6    | Band alarm   |            |
| 7    | 7    | 7    | System failure alarm (when error information happen) |            |
| 8    | 8    | 8    | Loop break alarm                                     | see fig 8  |
| 9    | 9    | 9    | Heater break alarm                                   | see fig 9  |
| 10   | 10   | 10   | Segment ending alarm in program control              | see fig 10 |
| 11   | 11   | 11   | Program ending alarm in program control              | see fig 11 |
| 12   | 12   |      | Time signal alarm                                    | see fig 12 |
| 13   | 13   |      | Program running alarm in program control             | see fig 13 |

**Table 4.(used in parameter InP1 )**  
input & temperature ranges selection

| TYPE | °C         | °F        |
|------|------------|-----------|
| K1   | 0~200      | 32~392    |
| K2   | 0~400      | 32~752    |
| K3   | 0~800      | 32~1472   |
| K4   | 0~1000     | 32~1832   |
| K5   | 0~1200     | 32~2192   |
| j1   | 0~200      | 32~392    |
| j2   | 0~400      | 32~752    |
| j3   | 0~800      | 32~1472   |
| j4   | 0~1000     | 32~1832   |
| j5   | 0~1200     | 32~2192   |
| t1   | -50~50     | -58~122   |
| t2   | -100~100   | -148~212  |
| t3   | -200~400   | -328~752  |
| r    | 0~1700     | 32~3092   |
| E    | 0~1000     | 32~1832   |
| S    | 0~1700     | 32~3092   |
| b    | 0~1800     | 32~3272   |
| n    | -200~1300  | -328~2372 |
| Pt1  | -50~50     | -58~122   |
| Pt2  | 0~100      | 32~212    |
| Pt3  | 0~200      | 32~392    |
| Pt4  | 0~400      | 32~752    |
| Pt5  | -200~600   | -328~1112 |
| jPt  | -200~500   | -328~932  |
| Lin  | -1999~9999 |           |

**Table 2. special alarm function selection**  
(used in parameter AL1M, AL2M, AL3M )

| AL1M | AL2M | AL3M | Special alarm mode selection                        |
|------|------|------|---|
| 0    | 0    | 0    | Normal  |
| 1    | 1    | 1    | Alarm with normal-close contact                     |
| 2    | 2    | 2    | Latch   |
| 3    | 3    | 3    | Alarm with normal-close contact and latch           |
| 4    | 4    | 4    | Alarm with inhibit                                  |
| 5    | 5    | 5    | Alarm with inhibit and normal-close contact         |
| 6    | 6    | 6    | Alarm with inhibit and latch                        |
| 7    | 7    | 7    | Alarm with inhibit , normal-close contact and latch |
| 8    |      |      | Alarm with on-delay timer                           |
| 9    |      |      | Alarm with on-delay timer but normal-close contact  |
| 10   |      |      | Alarm with soaking timer                            |
| 11   |      |      | Alarm with soaking timer but normal-close contact   |

**Table 3. output mode selection**  
(used in parameter OUTM )

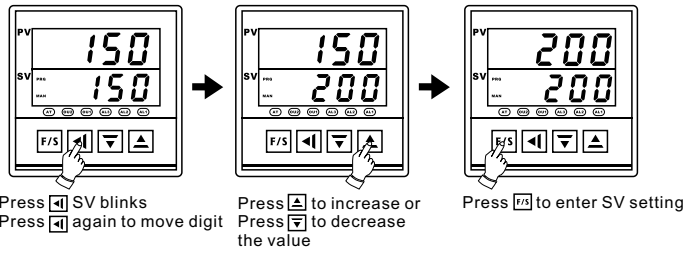
|   |   |
|---|---|
| 0 | Non   |
| 1 | Single output                                 |
| 2 | Dual output                                   |
| 3 | Motor value control output "a" contact        |
| 4 | Motor value control output b contact          |
| 5 | Single output with transmitter                |
| 6 | Single output with soft start                 |
| 7 | Single output with transmitter and soft start |
| 8 | Program control                               |
| 9 | Program control with transmitter              |

※NO.2~9 need to be ordered

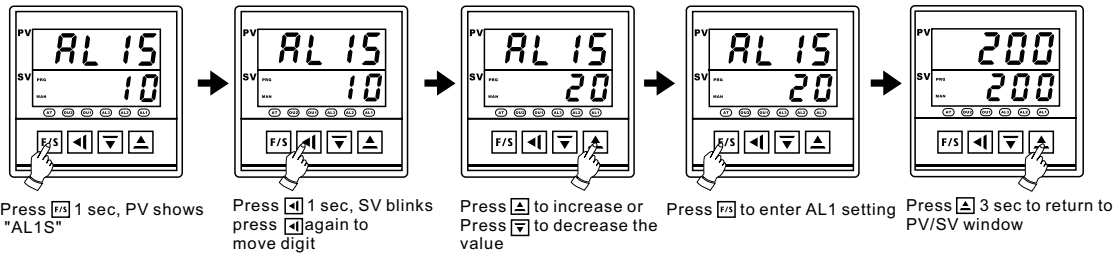
**Table 5.Error information**

| Display          | description                       |
|------------------|-----------------------------------|
| <i>in1E</i>      | Input 1 error                     |
| <i>AdCF</i>      | A/D converter failed              |
| <i>CJCE</i>      | Cold junction compensation failed |
| <i>in2E</i>      | Input 2 error                     |
| <i>PV</i> Blinks | PV exceeds set Ranges             |
| <i>rRnF</i>      | Ram failed                        |
| <i>intF</i>      | Interface failed                  |
| <i>AutF</i>      | Auto tuning failed                |

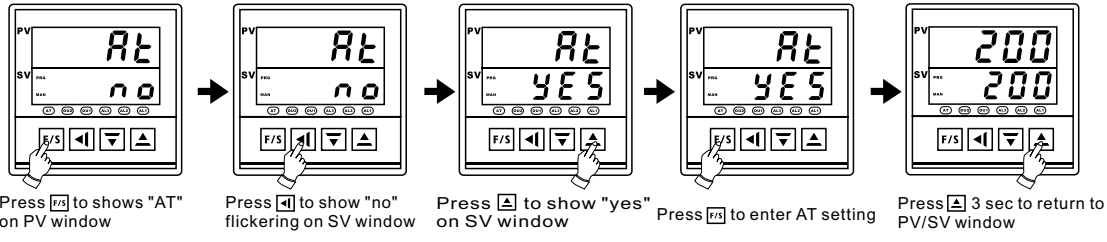
### A How to set "SV" example: SV set at 200 °C



### B How to set "AL1S,AL2S,AL3S" example: alarm 1 set at 20 °C

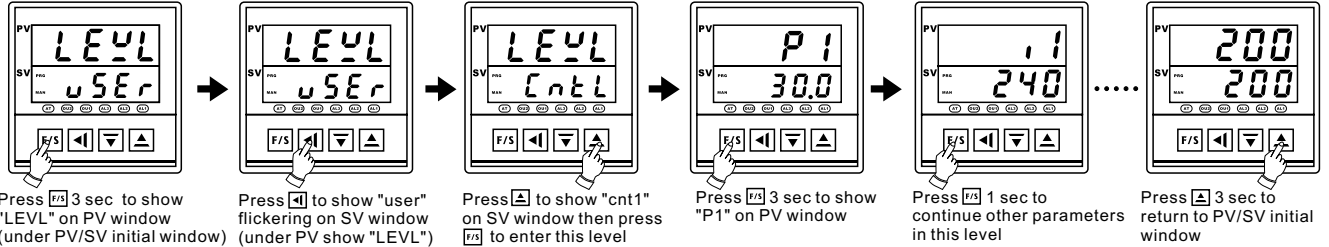


### C How to set "AT" (auto tuning)

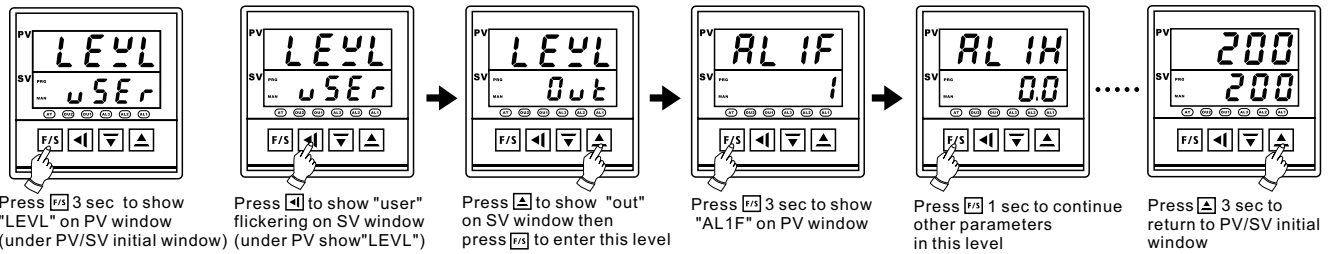


### D How to enter different "level" for setting parameter

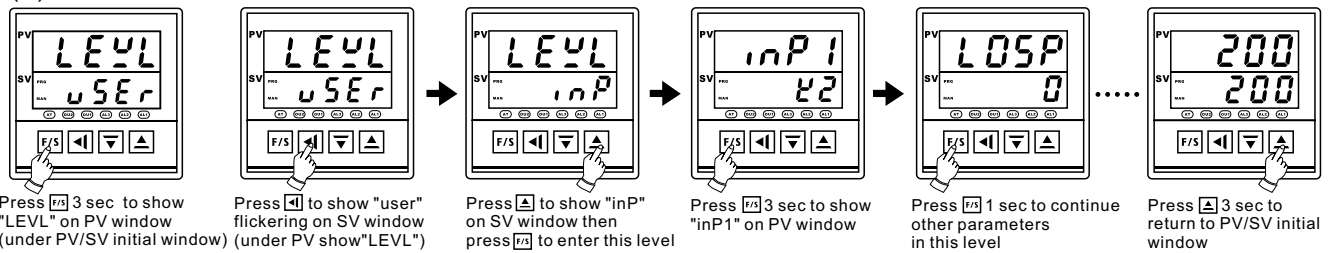
#### (1) Enter "CntL" level



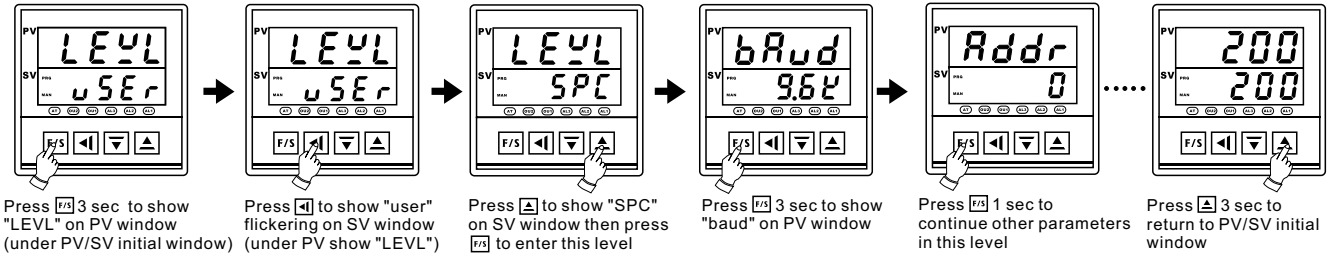
#### (2) Enter "Out" level



#### (3) Enter "inP" level

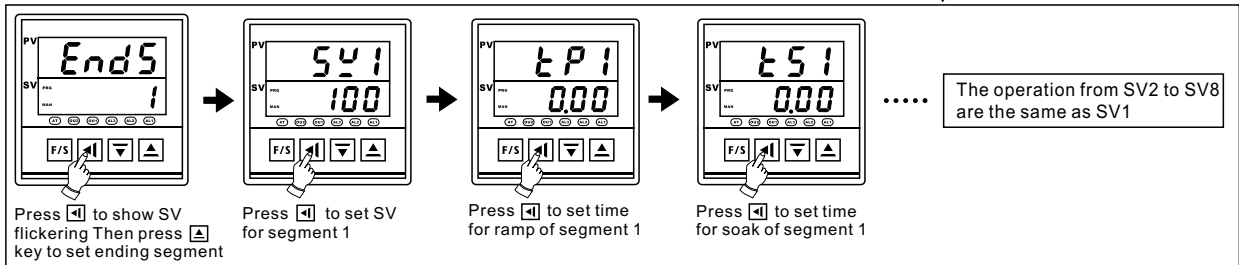
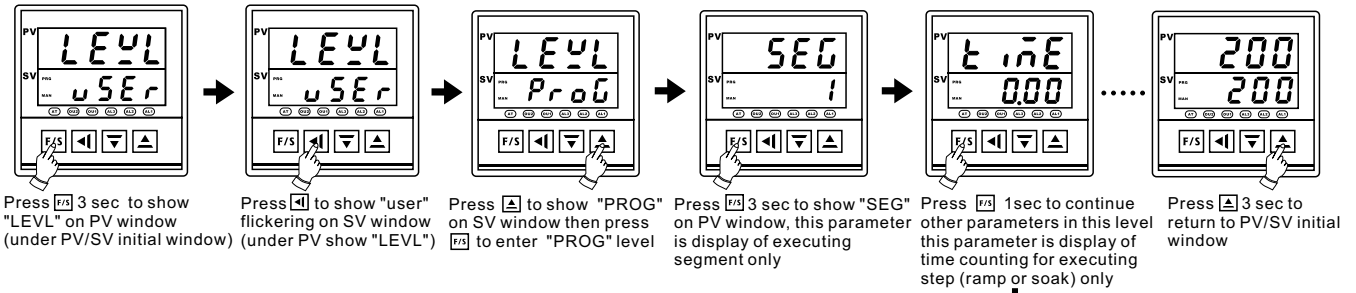


#### (4) Enter "SpC" level



#### (5) Enter program level

\* "OUTM" in "out" level must be selected at "8" or "9" (refer to fig 3)

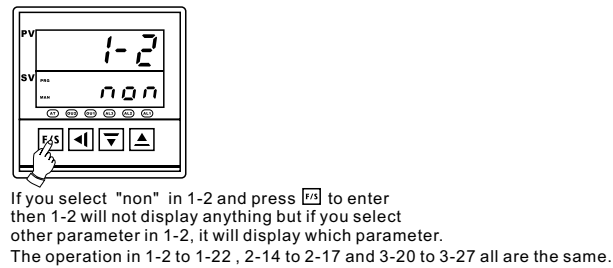
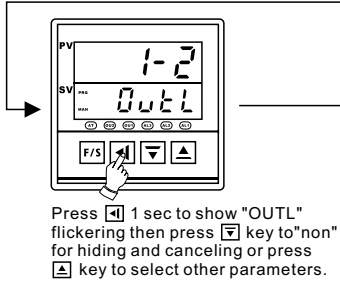
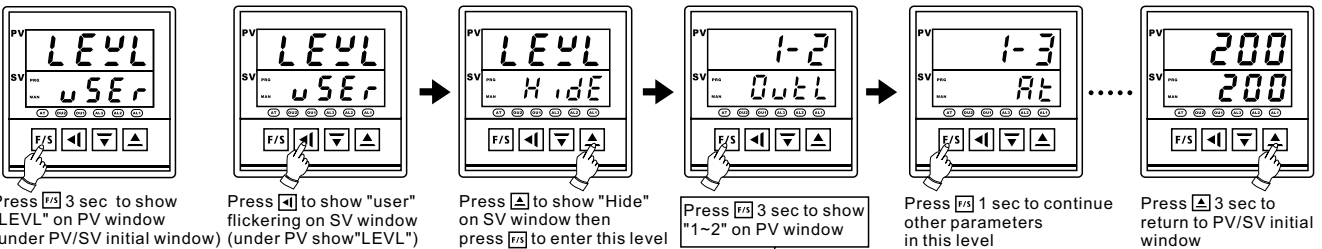


#### (6) Enter "Hide" level

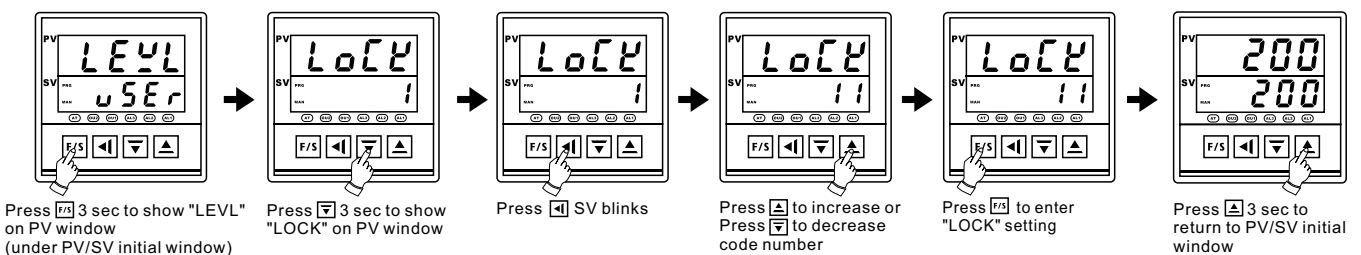
In this level, the user can arrange parameter order or hiding from NO. 1-2 to 1-22, 2-14 to 2-17 and 3-20 to 3-27

( please refer to level parameter flow chart in page 1),but same parameter can not be arranged in 2 positions in the same time,

for example you want to arrange "OUTL" to 1-3 you need to cancel it in 1-2 first. When you want to cancel or hide it you need to select "non" on the "SV"



#### E How to set "LoCK" function



## Code number for Lock function

|       |   |
|-------|---|
| 110   | all parameters are locked except PV     |
| 1101  | all parameters are locked except SV     |
| 111   | open"USER" level and above              |
| 122   | open"CNTL" level and above              |
| 1111  | open"OUT" level (Except OUTM )and above |
| 222   | open"INP" level and above               |
| 11100 | open"SPC" level and above               |
| 22100 | open"PROG"level and above               |
| 11122 | open"HIDE" level and above              |
| 1234  | open"USER" and "PROG" level only        |

## F. How to modify input

This series controller provides free input for T/C and RTD, it doesn't need to modify hardware except analog input.

### 1. Analog input hardware modification

(Refer to S1~S8 on PC board back)

S1 & S2 are shorted with COM. originally,

so it needs to open S1 or S1& S2 and to short some pads as drawing.

| INPUT   | S1 | S2 | S3 | S4 | S5 | S6 | S7 | S8 |
|---------|----|----|----|----|----|----|----|----|
| TC/RTD  | ○  | ○  | ✕  | ✕  | ✕  | ✕  | ✕  | ✕  |
| 0~20MA  | ✕  | ○  | ✕  | ✕  | ○  | ✕  | ✕  | ✕  |
| 4~20MA  | ✕  | ○  | ✕  | ✕  | ○  | ✕  | ✕  | ✕  |
| 0~100MV | ✕  | ✕  | ○  | ✕  | ✕  | ○  | ✕  | ✕  |
| 0~1V    | ✕  | ✕  | ✕  | ○  | ✕  | ○  | ✕  | ✕  |
| 0~5V    | ✕  | ✕  | ✕  | ✕  | ✕  | ○  | ✕  | ○  |
| 1~5V    | ✕  | ✕  | ✕  | ✕  | ✕  | ○  | ○  | ✕  |
| 0~10V   | ✕  | ✕  | ✕  | ✕  | ✕  | ○  | ✕  | ○  |

[○] short [✕] open

### 2. Analog input software modification


※Select "Lin" in "inpl" parameter

※Set "LoAn" in "inp" level to lowest range


※Set "HiAn" in "inp" level to highest range

### 3. Analog input calibration

※Enter "A1LS" parameter in "inp" level

※Provide signal for lowest range and wait for 3 sec then keep pressing  key

※Enter "A1HS" parameter in "inp" level

※Provide signal for highest range and wait for 3 sec then keep pressing  key

※Return to PV/SV initial window and provide signal for lowest range again then check if PV equals to LoAn

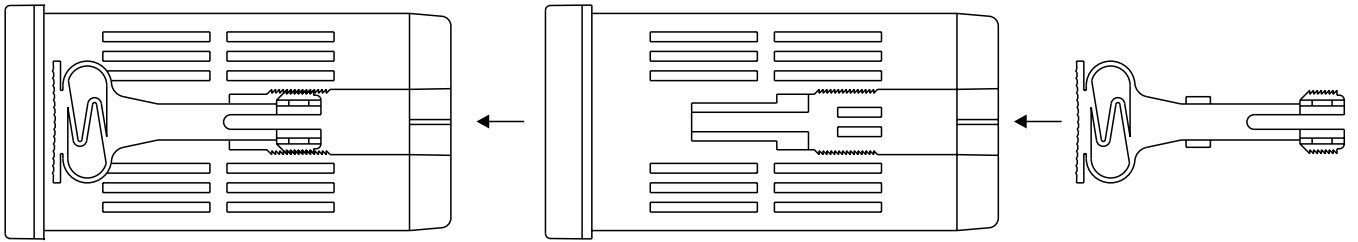
※Provide signal for highest range again then check if PV equals to HiAn

If it is not accuracy after calibrating, please repeat above procedure again

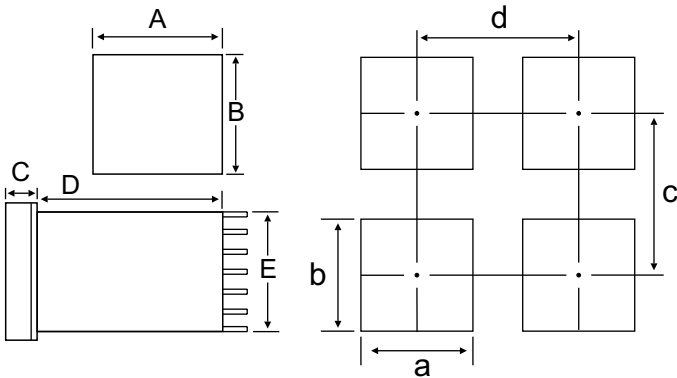
G. Communication Protocol (see fig 14)

| PARA | INDEX | PARA | INDEX | PARA | INDEX | PARA | INDEX |
|------|-------|------|-------|------|-------|------|-------|
| LEvL | 00    | AL1F | 30    | L1i1 | 60    | Sv7  | 90    |
| LoCK | 01    | AL1H | 31    | L1d1 | 61    | tP7  | 91    |
| Sv   | 02    | Al1t | 32    | L1Ar | 62    | tS7  | 92    |
| OutL | 03    | AL1m | 33    | L1P2 | 63    | Sv8  | 93    |
| At   | 04    | AL2F | 34    | L1i2 | 64    | tP8  | 94    |
| mAn  | 05    | AL2H | 35    | L1d2 | 65    | tS8  | 95    |
| AL1S | 06    | AL2t | 36    | L2P1 | 66    | 1-2  | 96    |
| AL1L | 07    | AL2m | 37    | L2i1 | 67    | 1-3  | 97    |
| AL1U | 08    | AL3F | 38    | L2d1 | 68    | 1-4  | 98    |
| AL2S | 09    | AL3H | 39    | L2Ar | 69    | 1-5  | 99    |
| AL2L | 0A    | AL3t | 3A    | L2P2 | 6A    | 1-6  | 9A    |
| AL2U | 0B    | AL3m | 3B    | L2i2 | 6B    | 1-7  | 9B    |
| AL3S | 0C    | Act  | 3C    | L2d2 | 6C    | 1-8  | 9C    |
| AL3L | 0D    | Outm | 3D    | L3P1 | 6D    | 1-9  | 9D    |
| AL3U | 0E    | O1LS | 3E    | L3i1 | 6E    | 1-10 | 9E    |
| SOAK | 0F    | O1HS | 3F    | L3d1 | 6F    | 1-11 | 9F    |
| rAmP | 10    | AO   | 40    | L3Ar | 70    | 1-12 | A0    |
| PvoF | 11    | O2LS | 41    | L3p2 | 71    | 1-13 | A1    |
| Pvrr | 12    | O2HS | 42    | L3i2 | 72    | 1-14 | A2    |
| SvoF | 13    | t1SS | 43    | L3d2 | 73    | 1-15 | A3    |
| Ct   | 14    | t1On | 44    | L4P1 | 74    | 1-16 | A4    |
| HbA  | 15    | t1ES | 45    | L4i1 | 75    | 1-17 | A5    |
| LbA  | 16    | t1oF | 46    | L4d1 | 76    | 1-18 | A6    |
| Lbd  | 17    | t2SS | 47    | L4Ar | 77    | 1-19 | A7    |
| rPtm | 18    | t2On | 48    | L4p2 | 78    | 1-20 | A8    |
| P1   | 19    | t2ES | 49    | L4i2 | 79    | 1-21 | A9    |
| i1   | 1A    | t2oF | 4A    | L4d2 | 7A    | 1-22 | AA    |
| d1   | 1B    | inP1 | 4B    | SEG  | 7B    | 2-14 | AB    |
| Ct1  | 1C    | LoSP | 4C    | TimE | 7C    | 2-15 | AC    |
| HSt1 | 1D    | HiSP | 4D    | EndS | 7D    | 2-16 | AD    |
| AotF | 1E    | LoAn | 4E    | Sv1  | 7E    | 2-17 | AE    |
| Ar   | 1F    | HiAn | 4F    | tP1  | 7F    | 3-20 | AF    |
| P2   | 20    | A1LS | 50    | tS1  | 80    | 3-21 | B0    |
| i2   | 21    | A1HS | 51    | Sv2  | 81    | 3-22 | B1    |
| d2   | 22    | unit | 52    | tP2  | 82    | 3-23 | B2    |
| Ct2  | 23    | dp   | 53    | tS2  | 83    | 3-24 | B3    |
| HSt2 | 24    | FiLt | 54    | Sv3  | 84    | 3-25 | B4    |
| db   | 25    | inP2 | 55    | tP3  | 85    | 3-26 | B5    |
| SSv  | 26    | A2LS | 56    | tS3  | 86    | 3-27 | B6    |
| Sout | 27    | A2HS | 57    | Sv4  | 87    |      |       |
| StmE | 28    |      |       | tP4  | 88    |      |       |
| rUCy | 29    | bAud | 59    | tS4  | 89    |      |       |
| rPt  | 2A    | Addr | 5A    | Sv5  | 8A    |      |       |
| StAt | 2B    | LEv1 | 5B    | tP5  | 8B    |      |       |
| PvSt | 2C    | LEv2 | 5C    | tS5  | 8C    |      |       |
| wAit | 2D    | Lev3 | 5D    | Sv6  | 8D    |      |       |
| Pid  | 2E    | LvSL | 5E    | tP6  | 8E    |      |       |
| EndP | 2F    | L1P1 | 5F    | tS6  | 8F    |      |       |
|      |       |      |       |      |       | Pv   | 100   |

# Mounting procedures

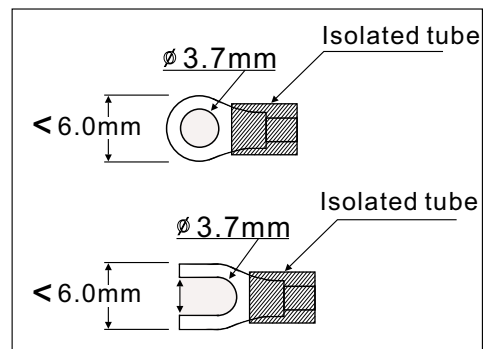


# Dimension

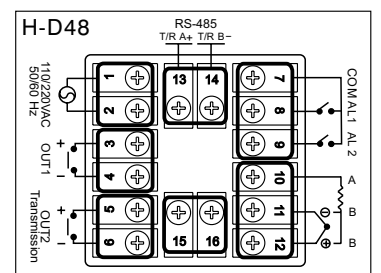
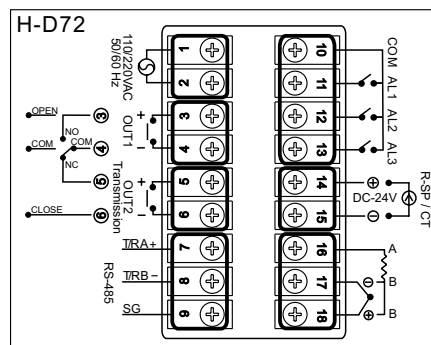
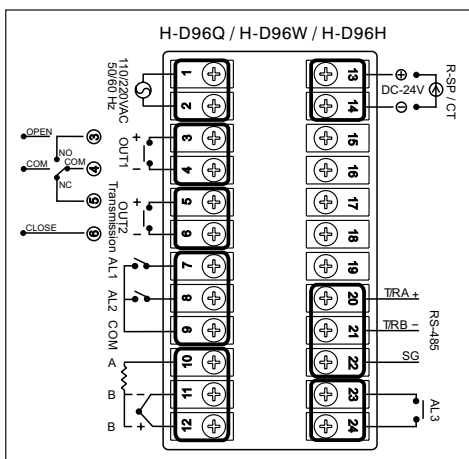


| Type   | A  | B  | C    | D  | E  | a                                | b                                | c   | d   |
|--------|----|----|------|----|----|----------------------------------|----------------------------------|-----|-----|
| H-D96Q | 96 | 96 | 10.5 | 83 | 90 | 91 <sup>+0.5</sup> <sub>-0</sub> | 91 <sup>+0.5</sup> <sub>-0</sub> | 120 | 120 |
| H-D72  | 72 | 72 | 10.5 | 83 | 67 | 68 <sup>+0.5</sup> <sub>-0</sub> | 68 <sup>+0.5</sup> <sub>-0</sub> | 100 | 100 |
| HD96W  | 96 | 48 | 10.5 | 83 | 43 | 91 <sup>+0.5</sup> <sub>-0</sub> | 46 <sup>+0.5</sup> <sub>-0</sub> | 70  | 120 |
| H-D96H | 48 | 96 | 10.5 | 83 | 90 | 46 <sup>+0.5</sup> <sub>-0</sub> | 91 <sup>+0.5</sup> <sub>-0</sub> | 120 | 70  |
| H-D48  | 48 | 48 | 10.5 | 83 | 45 | 46 <sup>+0.5</sup> <sub>-0</sub> | 46 <sup>+0.5</sup> <sub>-0</sub> | 70  | 70  |

# Available terminal



# External terminal



## SPECIFICATIONS

|                        |                                  |  |
|------------------------|----------------------------------|--|
| PV Input               | Type of Input                    | TC (K,J,T,R,E,S,B,N)<br>RTD (Pt100, JPt100)<br>Linear(1-5V, 4-20mA)                                |
|                        | Input Sampling Time              | 300 ms   |
|                        | PV/SV Indication                 | 4-digit  |
| Indication             | Constant Value Storage System    | Non-volatile memory (E <sup>2</sup> PROM)  |
|                        | Control Mode                     | Proportional Band ( P )<br>Integral Time ( I )<br>Derivative Time ( D )<br>Cycle Time<br>Dead Band |
| Control Mode           | Proportional Band ( P )          | 0.0~3000   |
|                        | Integral Time ( I )              | 0~3600   |
|                        | Derivative Time ( D )            | 0~900  |
|                        | Cycle Time                       | 0~150  |
|                        | Dead Band                        | 0.0~200.0  |
| Output                 | Relay Output Relay               | Contact, SPDT 3A/240VAC  |
|                        | Voltage Output                   | Voltage Pulse  |
|                        | Linear Output                    | 4~20mA, 1-5V ,   |
|                        | Motor Control Output             | Open loop motor valve  |
| Alarm                  | Channel                          | 3 Channels (Optional)  |
| Communication          | Type of Communication            | RS-232, RS-485   |
| General Specifications | Power Supply Voltage & Frequency | AC 90~260V, 50/60Hz  |
|                        | Power Consumption                | <3.5VA   |
|                        | Ambient Temperature              | -10°C ~ 55°C   |
|                        | Ambient Humidity                 | 0~80% RH   |

## ORDERING INFORMATION

A      B C D E    F G H

H - D48 - 1101 - 000

### A: Type (Dimension)

D48 = 48x48mm ( DIN 1/16 ), D96H = 48x96mm ( DIN 1/8 ),  
 D96W = 96x48mm ( DIN 1/8 ), D96Q = 96x96mm ( DIN 1/4)),  
 D72 = 72x72mm

### B: INput

1=K 7=B  
 2=J 8=N  
 3=T 9=DIN/PT  
 4=R A=J IN/ PT  
 5=E B=LINEAR  
 6=S

### C: Output 1

0=NONE  
 1=RELAY  
 2=PULSED  
 3=4-20M  
 4=1-5V  
 5=open loop  
   motor valve

### D: Output 2

0=NONE  
 1=RELAY  
 2=PULSED  
 3=4-20MA  
 4=1-5V  
 5=Transmission

### E: Alarm

0 =NONE  
 1 =ALARM\*1  
 2 =ALARM\*2  
 3 =ALARM\*3

### F: Addition

0=NONE  
 1=DC-24V  
 2=REMOTE-SP  
 3=CT

### G: Communication

0=NONE  
 1=RS-485  
 2=RS-232

### H: Program

0=NONE  
 1=PROGRAM